

# Introduction to Artificial Intelligence

## Evolutionary Computation

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<https://edux.fit.cvut.cz/courses/BIE-ZUM/>

## Summary of Previous Lecture

- We introduced local search algorithms.
  - ▶ Operates using a single current configuration (candidate solution) and search in the neighborhood for better configuration to move in.
- We defined optimization problem.
  - ▶ The goal is to find the best configuration according to some objective function, path is irrelevant.
- Hill-climbing
  - ▶ Continually moves in the direction of increasing objective function.
- Simulated annealing
  - ▶ Combination of random hill-climbing search and Metropolis algorithm allows to move with certain probability to worse than current solution.
- Tabu search
  - ▶ Uses memory structures to maintain a history and prevent recent states being revisited.

# Evolutionary Computation

- Family of global meta-heuristic or stochastic optimization methods.
- Algorithms typically imitate some principle of natural evolution as method to solve optimization problems, e.g:
  - ▶ natural selection, survival of the fittest (Charles Darwin),
  - ▶ theory of genetic inheritance (Gregor Johann Mendel).
- Iteratively improves, "breeds", population of candidate solutions by selecting and recombining good quality candidates.
- Typically applied for black box problems where optimization is expensive.

# Evolutionary Computation Techniques

- Gene expression programming
- Genetic algorithm
- Genetic/Evolutionary programming
- Evolution strategy
- Swarm intelligence
  - ▶ Ant colony optimization
  - ▶ Particle swarm optimization
  - ▶ Bees algorithm
  - ▶ Artificial immune systems
- Differential evolution
- Cultural algorithm
- Harmony search
- and many others...

# Evolution of Chordate phylum



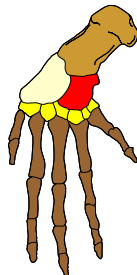
human



dog



bird



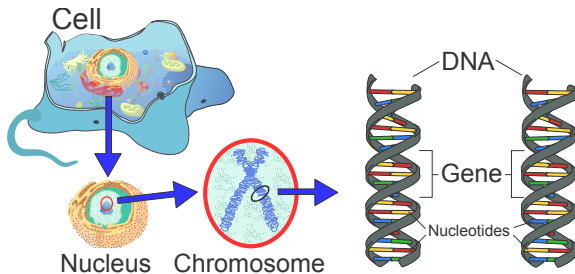
whale

# Practical use of Evolutionary Computation Techniques

- computer programs, functions fitting,
- automotive design, racing cars,
- robotics, design and behavior,
- hardware design, electronic circuits,
- computer gaming,
- encryption, code breaking,
- molecular design, chemistry and medicine,
- finance and investment strategies,
- neural networks design,
- ...

## Biological Terminology

- Living organisms consist of cells. Cell's nucleus contains **chromosomes** that encode its DNA.
- A chromosome can be conceptually divided into **genes**, stretches of DNA encoding some trait, such as eye color, height etc.
- The different possible configurations for a trait are called **alleles** (e.g. blue, brown).
- Each gene is located at a particular position on the chromosome called **locus**.

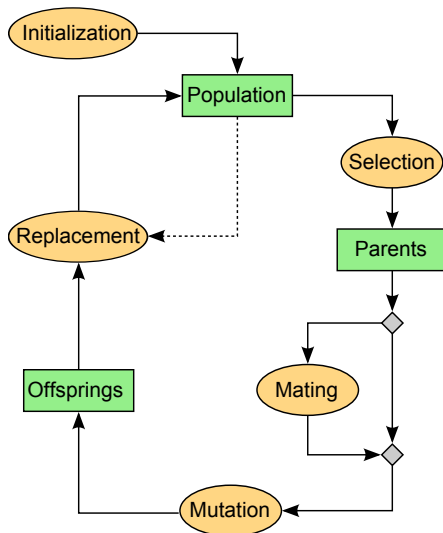


## Biological Terminology

- The complete collection of genetic material is called organism's **genome**.
- **Genotype** refers to a particular set of genes contained in a genome. Two individuals with identical genomes are said to have the same genotype.
- **Phenotype** is physical (or mental) characteristics of an organism (e.g. eye color, height, intelligence).
- **Recombination** (or **crossover**) is sexual reproduction when genes between two **parent** chromosomes are exchanged to form an **offspring**.
- **Mutation** is process in which single nucleotides (elementary bits of DNA) are changed from parent to offspring (often resulting from copying errors).
- The **fitness** of an organism is typically defined as the probability that the organism will live to reproduce (**viability**) or as a function of the number of offspring the organism has (**fertility**)



# General Evolutionary Computation Scheme



## Evolutionary Computation Terminology

- The term **chromosome** refers to a candidate solution to a problem, typically encoded in a form of binary string.
- The **genes** are either single **bits** or short blocks of adjacent bits that encode a particular element of the candidate solution.
- The **genotype** of an individual is simply the configuration that individual's chromosome. It is a **grammar** of a solution.
- There is often no notion for **phenotype** in GA. We can see it as a **semantics** of a solution.
- An **allele** is one letter of chosen alphabet (e.g. 0 or 1 for bit)
- **Mutation** randomly changes the allele values of some locations in the chromosome (e.g. flipping random bit in binary string).
- **Crossover** is a process of exchanging genetic material between two single chromosome parents, i.e. exchanging part of configuration.
- Population in each iteration is called a **generation**.
- The entire set of generations is called a **run**.

# Genetic Algorithm

- Invented at University of Michigan by John Holland in 1960s.
- Probably the most known evolutionary algorithm.
- From the beginning the goal was to formally study the phenomenon of natural adaptation and ability of general incorporation in problem solving.
- Result is universal "black box solver" for optimization using binary strings.

## Genetic algorithm

Let  $\mathbf{x} \in \{0, 1\}^n$  be a binary string (chromosome) of a length  $n$  and let  $f(\mathbf{x})$  be a fitness function such that

$$f : \{0, 1\}^n \rightarrow \mathbb{R},$$

**genetic algorithm** solves an optimization problem

$$\mathbf{x}^* = \arg \max_{\mathbf{x} \in \{0, 1\}^n} (f(\mathbf{x})).$$

# Genetic Algorithm

- 1 INITIALIZATION generate initialization population.
- 2 Calculate the fitness of each chromosome in the population.
- 3 Repeat the following steps until  $n$  offsprings have been created:
  - (I) SELECTION Select a pair of parent chromosomes from the current population, the probability of selection being an increasing function of fitness.
  - (II) CROSSOVER With probability  $p_c$  (the "crossover probability" or "crossover rate"), cross over the pair to form two offspring. If no crossover takes place, form two offspring that are exact copies of their respective parents.
  - (III) MUTATION Mutate the offspring at each locus with probability  $p_m$  (the mutation probability or mutation rate), and place the resulting chromosomes in the new population.
- 4 Replace the current population with the new population.
- 5 Check stopping criteria (or convergence) and
  - ▶ terminate, or
  - ▶ go to step 2.

# Population Initialization

## Non-informed initialization

- Generates population of binary vectors randomly.

## Informed initialization

- Population is generated with some knowledge.
  - ▶ Using simple heuristics.
  - ▶ Seeding with known good quality individuals.
- Risk that whole population will be placed in local optima that will be difficult or impossible to leave using crossover and mutation.

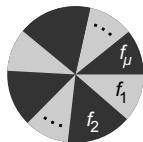
## Selection

- Selection operators chooses good quality chromosomes from the population to be reproduced. The fitter the chromosome, the more times it is likely to be selected to reproduce.
- **Elitism** is an addition to selection operator, which forces to retain some number of best individuals of each generation.

### Roulette-wheel selection

- Equivalent to giving each individual a slice of a circular roulette wheel equal in area to the individual's fitness.

$$P_i(x) = \frac{f_i(x)}{\sum_{j=1}^{\mu} f_j(x)}$$

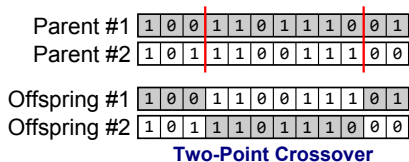
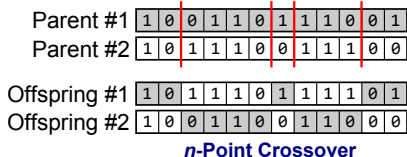
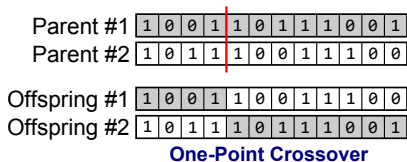


### Tournament selection

- Randomly pick a small subset of chromosomes from the population and the chromosome with highest fitness becomes a parent.
- Not need to sort population by fitness!

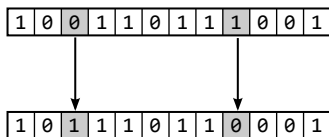
# Crossover

- Crossover operator combine or exchanges subparts of two chromosomes.
- Depends greatly on the problem and the encoding strategy.
- For some problems (with specific encoding) is even not used and evolution depends only on mutation.



## Mutation

- Mutation operator randomly flips some of the bits in a chromosome.
- Mutation can occur at each bit position in a string with some probability  $p_m$ , usually very small (e.g., 0.001).




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### Algorithm 1 bitflip\_mutation( $\mathbf{x}$ )

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```

for  $i \leftarrow 1$  to  $n$  do
  if  $\text{random}(\langle 0, 1 \rangle) < p_m$  then
     $\mathbf{x}[i] \leftarrow \neg \mathbf{x}[i]$ 
  end if
end for

```

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# Genetic Algorithm Pseudocode

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## Algorithm 2 Genetic Algorithm (GA)

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```
 $\mathcal{P} \leftarrow \{\}$   
for  $i \leftarrow 1$  to  $\mu$  do  
   $\mathbf{x} \leftarrow \text{random\_individual}()$   
   $\mathcal{P} \leftarrow \mathcal{P} \cup \{(\mathbf{x}, f(\mathbf{x}))\}$   
end for  
repeat  
   $\mathcal{O} \leftarrow \{\}$   
  for  $i \leftarrow 1$  to  $\frac{\mu}{2}$  do  
     $\mathbf{p}_1 \leftarrow \text{selection}(\mathcal{P})$   
     $\mathbf{p}_2 \leftarrow \text{selection}(\mathcal{P})$   
     $(\mathbf{o}_1, \mathbf{o}_2) \leftarrow \text{crossover}(\mathbf{p}_1, \mathbf{p}_2)$   
     $\tilde{\mathbf{o}}_1 \leftarrow \text{mutate}(\mathbf{o}_1)$   
     $\tilde{\mathbf{o}}_2 \leftarrow \text{mutate}(\mathbf{o}_2)$   
     $\mathcal{O} \leftarrow \mathcal{O} \cup \{(\tilde{\mathbf{o}}_1, f(\tilde{\mathbf{o}}_1)), (\tilde{\mathbf{o}}_2, f(\tilde{\mathbf{o}}_2))\}$   
  end for  
   $\mathcal{P} \leftarrow \mathcal{O}$   
until termination condition is met
```

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# Parameters of Genetic Algorithm

- Initial population.
- Size of the population.
- Mutation rate.
- Crossover rate.
- Number of generations.

Moreover we have to decide about

- Encoding strategy.
- Fitness function.
- Crossover operators.
- Elitism.
- etc. . .

# Knapsack Problem

Given

- knapsack with weight limit  $W$ ,
- set of items  $T = \{t_1, t_2, \dots, t_n\}$  with weight  $w(t_i)$  and value  $v(t_i)$ .

The goal is to find a subset  $Z \subseteq T$  with maximal possible value so that the total weight is less than or equal to a given limit

$$\arg \max_{Z \subseteq T} \sum_{z \in Z} v(z) \quad \text{t.ž.} \quad \sum_{z \in Z} w(z) \leq W.$$

The knapsack problem is **NP-hard**, it means it does not exist an algorithm that solves the problem in polynomial time.

However, we can find near-optimal solution with genetic algorithm.

# Knapsack Problem

- A chromosome can be represented in a binary string (array) having size equal to the number of the items.
- Each element from this array denotes whether an item is included in the knapsack ("1") or not ("0").
- Trivial fitness:

$$f(\mathbf{x}) = \begin{cases} \sum_{z \in \{t_j | x_j=1\}} v(z), & \text{pokud } \sum_{z \in \{t_j | x_j=1\}} w(z) \leq W, \\ 0, & \text{pokud } \sum_{z \in \{t_j | x_j=1\}} w(z) > W \end{cases}$$

- Can we do it better?

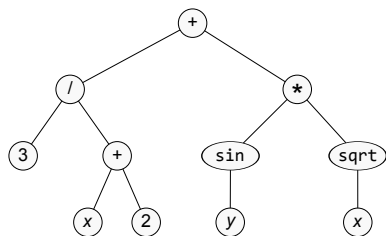
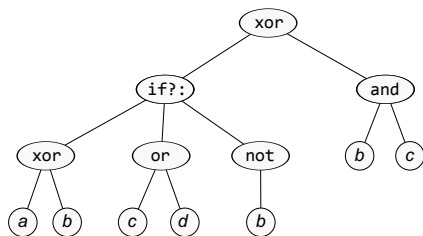
# Genetic Programming

- Invented at Sanford University by J.R. Koza in 1960s.
- Motivation was general automatic programming.
- First use of genetic programming was to evolve Lisp programs to perform various tasks.
- More flexible than fixed chromosome, size of instance is part of evolution.
- Genotype is represented in a form of syntax tree.

# Syntax Tree

Syntax tree consists of :

- **terminals** (leaves) –  $T$ 
  - ▶ inputs of program, independent variables
- **functions** (internal nodes) –  $F$ 
  - ▶ e.g. arithmetic operations, algebraic functions, logic functions etc.
- The sets of available functions and terminals form the **primitive set** of the genetic programming system.

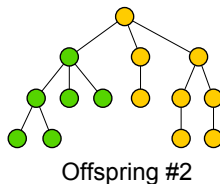
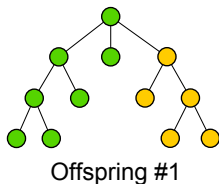
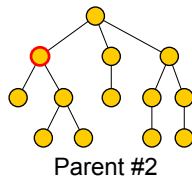
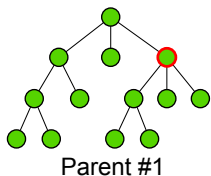


# Population Initialization

- Typically, individuals in the initial population are generated randomly.
- However, since it is not so trivial (such as generate random binary string) number of different approaches exist.
- First defined (and also simplest) methods are:
  - ▶ **GROW**
    - ★ generated tree has depth  $d \leq D_{max}$ ,
    - ★ nodes in depth  $d < D_{max}$  are randomly chosen from  $F \cup T$ ,
    - ★ nodes in depth  $d = D_{max}$  are randomly chosen from  $T$ .
  - ▶ **FULL**
    - ★ generated tree has depth  $d = D_{max}$ ,
    - ★ nodes in depth  $d < D_{max}$  are randomly chosen from  $F$ ,
    - ★ nodes in depth  $d = D_{max}$  are randomly chosen from  $T$ .
  - ▶ **Ramped half-and-half**
    - ★ half of the initial population is constructed using full and half using grow.
  - ▶ **PTC1/2** (Probabilistic Tree-Creation)
    - ★ generates tree with user defined expected size  $E_{tree}$ ,
    - ★ to each function  $f_i \in F$  and terminal  $t_i \in T$  are assigned probabilities  $p_{f_i}$  to be chosen  $f_i$  when function is needed respectively  $p_{t_i}$  to be chosen  $t_i$  when terminal is needed

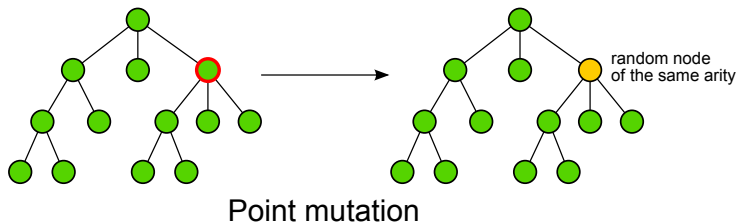
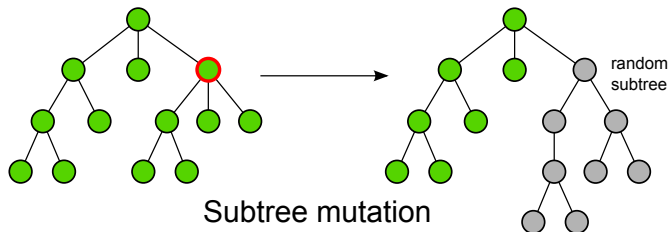
## Subtree Crossover

- Given two parents, subtree crossover randomly selects a crossover point in each parent tree.
- Two offsprings are created by replacing the subtrees rooted at the crossover points of both parents.

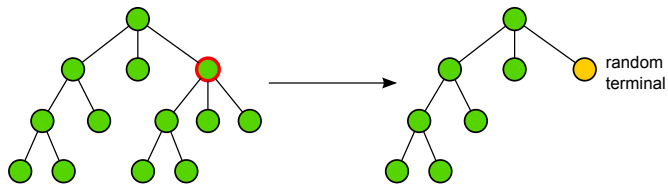




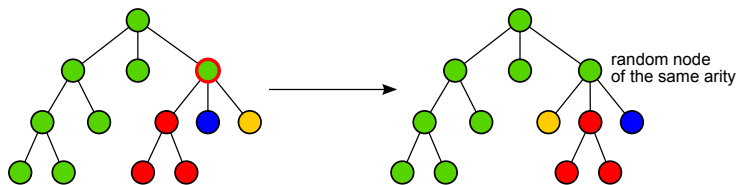
# Mutation



# Mutation



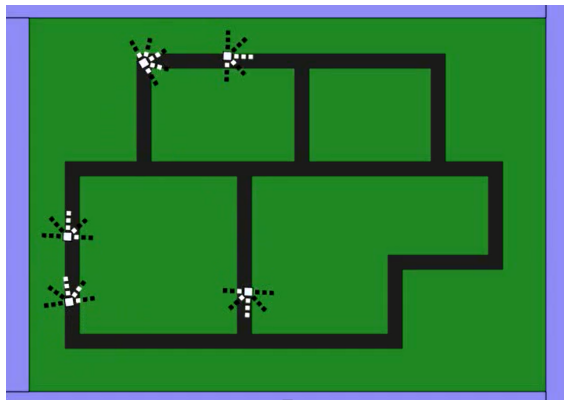
Shrink mutation



Permutation mutation

## Example

Goal: Evolve robots driving on roads. Fitness is the average speed.



<http://www.youtube.com/watch?v=lmPJekRs8gE>

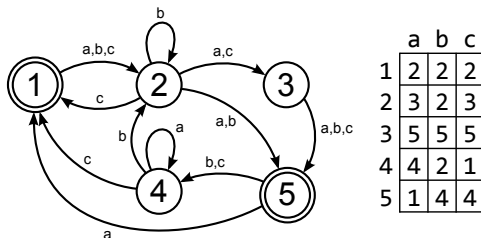
# Evolutionary Programming

- Invented at University of California by L.J.Fogel in 1960s.
- Motivation was to generate alternative approach to artificial intelligence.
- One population of solutions, reproduction is only by mutation.
- Early versions of EP applied to the evolution of transition table of finite state machines.

# Finite State Machine

State machine is described by:

- initial and final state,
- set of states,
- transition table.

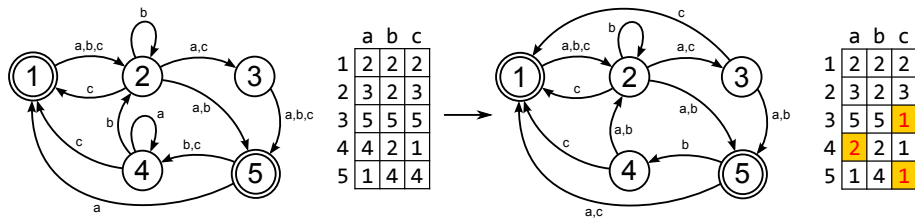


	a	b	c
1	2	2	2
2	3	2	3
3	5	5	5
4	4	2	1
5	1	4	4

# Mutation

Five possible modes of mutation of state machine:

- add a state,
- delete a state,
- change the start state,
- change an output symbol,
- change a state transition.



# Evolution Strategies

- Invented at Technische Universität Berlin by I. Rechenberg and H.P. Schwefel in 1960s.
- Based on the concept of the "evolution of evolution".
- Each individual is represented by its genotype and strategy parameters.
- Both genotype and strategy parameters are evolved.
- Mutated individuals are only accepted if fitness of parent is improved.

# Selection

- First version  $(1 + \lambda)$ -ES,
  - ▶ one parent generates  $\lambda$  offsprings,
  - ▶ the best of the offsprings becomes parent of next generation,
  - ▶ note the similarity with hill-climbing!
  
- Advanced version  $(\mu + \lambda)$ -ES and  $(\mu, \lambda)$ -ES
  - ▶  $\mu$  parents generates  $\lambda$  offsprings,
  - ▶  $(\mu + \lambda)$ -ES selects from these  $\mu + \lambda$  individuals  $\mu$  best to the next generation.
  - ▶  $(\mu, \lambda)$ -ES selects to the next generation  $\mu$  best only from offsprings.



# Mutation

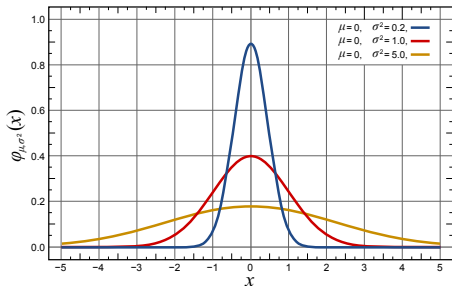
- **Gaussian mutation** - to each individual is added Gaussian distributed noise.

$$\mathbf{x}'(t) = \mathbf{x}(t) + N(0, \sigma(t))$$

- Adaptation of strategy parameters

- ▶ Based on the 1/5 success rule

- ★  $\sigma$  is increased if the relative frequency of successful mutations over a certain period is larger than 1/5
- ★ otherwise  $\sigma$  is decreased



# Self Adaptation

- Each individual is represented by its genotype and strategy parameters

$$\mathcal{X}(t) = (\mathbf{x}(t), \sigma(t))$$

$x(t) \in \mathbb{R}^n$  represents the genotype,  
 $\sigma$  represents the deviation strategy parameter vector.

- Both genotype and strategy parameters are evolved.
- Strategy parameters are self-adapted to determine
  - ▶ best search direction, and
  - ▶ maximum step size per dimension.

# Crossover

- In the first version offspring was generated only through mutation.
- Newer versions defined crossover.
  - ▶ **Discrete** – two parents are randomly selected and recombined using discrete, multipoint crossover.
  - ▶ **Intermediate** – the offspring is a weighted average of the parents.
  - ▶ **Arithmetic** – the offspring is arithmetic average of the parents.
- Extension  $(\mu/\rho \uplus \lambda)$ -ES indicates that  $\rho$  parents are used per application of the crossover operator,
  - ▶  $\rho = 1 \dots$  standard  $(\mu \uplus \lambda)$ -ES,
  - ▶  $\rho = 2 \dots$  local crossover,
  - ▶  $\rho < \rho \leq \mu \dots$  global crossover.